

# An envelope for errors in hydrological model output caused by sampling and averaging

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# Outline

- 1 Motivation
  - Models in hydrology
  - Problem statement
- 2 Effect of Error Envelope
  - A simple linear reservoir
  - A switch with hysteresis

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# Types of systems.

- River basins (also known as catchments)
- Series of Reservoirs
- Villages and cities

# Questions.

- Model to find risk of floods
- Model to find optimal operation strategy
- Model to avoid storm drain or sewer overflow

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# Model calibration.

- Preferably automated
- Input averaged over time intervals
- Output at discrete points in time

# Problem.

- Penalty function for optimization
- Model may not see details of input
- Parameters may have overlapping effects



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# Example

- parking lot
- roof

# The Functions.

- Precipitation intensity  $p(t)$  (millimeters per hour)
- Dynamic storage  $s(t)$  (depth in millimeters)
- run-off  $q(t) = c_0 s(t)$  (millimeters per hour)

# The model

$$\dot{s} = p(t) - c_0 R(s)$$

$$s(t_0) = s_0$$

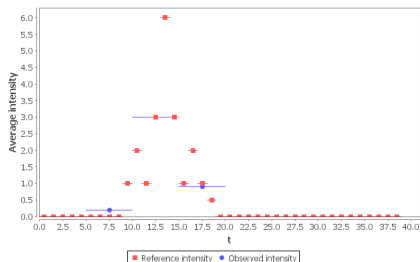
$$R(s) = \begin{cases} 0 & s \leq 0 \\ s & s > 0 \end{cases}$$

# The observations.

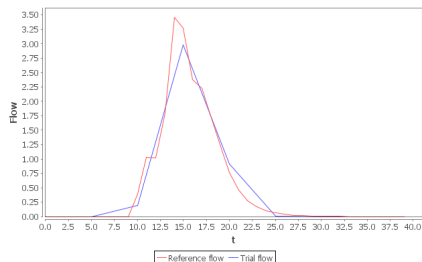
- Rain gauge data  $P_k = \int_{t=t_k}^{t_{k+1}} p(t) dt$  (millimeters)
- Runoff data  $q_k = q(t_k)$

# Optimization without Intervals.

**Intensities**

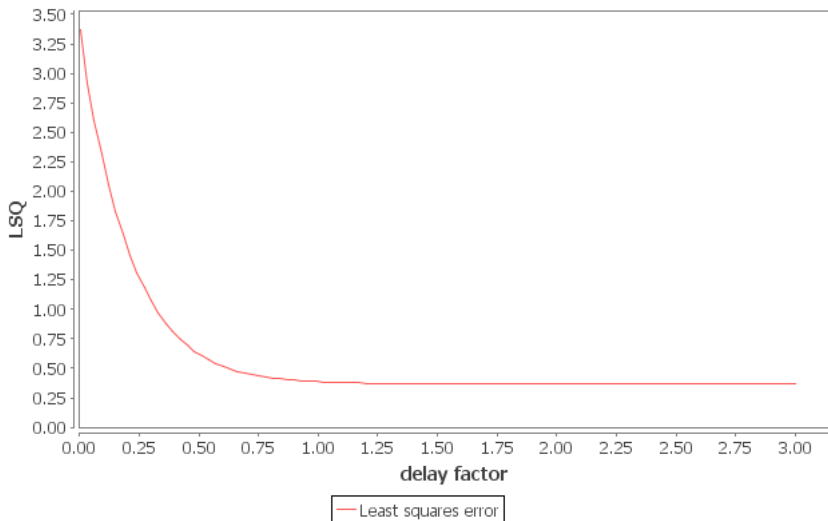


**Flows**



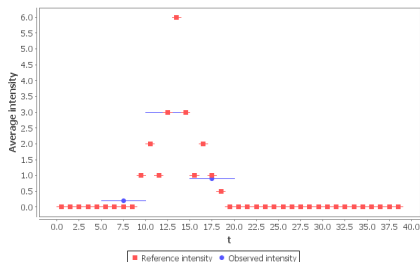
# Least Squares Error.

## Errors

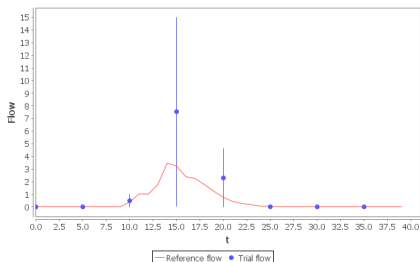


# Optimization with Intervals.

**Intensities**



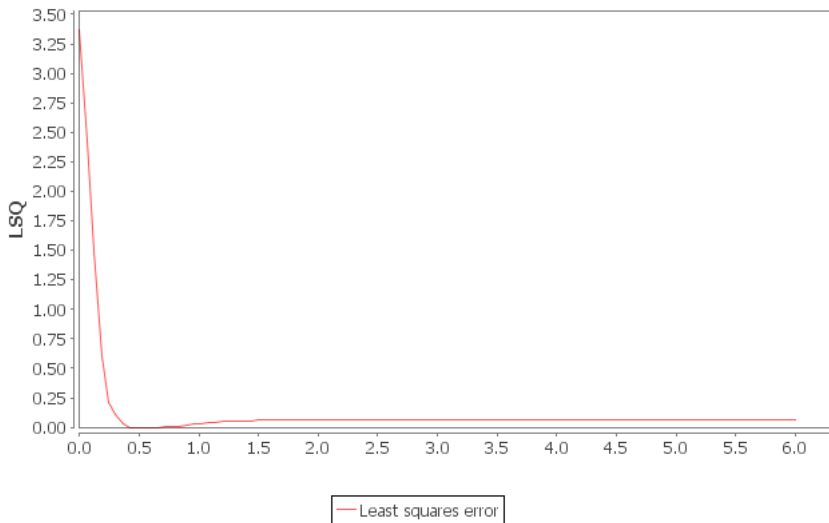
**Flows**





# Least Squares Error

## Errors



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- Section of a sewer system that is emptied by a pump

# The Functions.

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- Dynamic storage  $s(t)$  (depth in millimeters)
- run-off  $q(t) = c_0 s(t)$  (millimeters per hour)

# The model

$$\dot{s} = p(t) - c_0 u(s)$$

$$\dot{u} = H(1 - 2u(s)) \delta(s - s_{\text{on}}) - H(2u(s) - 1) \delta(s - s_{\text{off}})$$

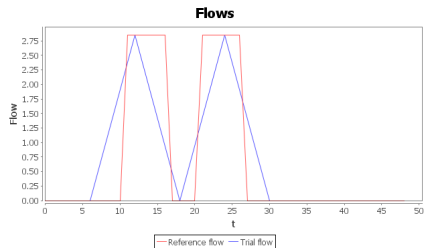
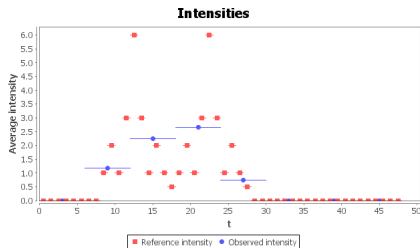
$$s(t_0) = s_0$$

$$H(s) = \begin{cases} 0 & s < 0 \\ 1 & s > 0 \end{cases}$$

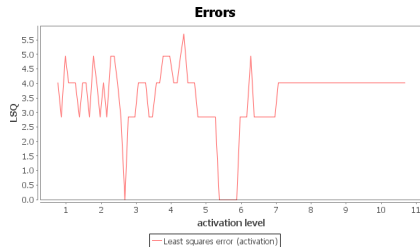
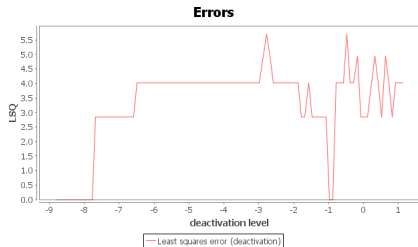
## The observations.

- Rain gauge data  $P_k = \int_{t=t_k}^{t_{k+1}} p(t) dt$  (millimeters)
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# Optimization without Intervals.



# Least Squares Error

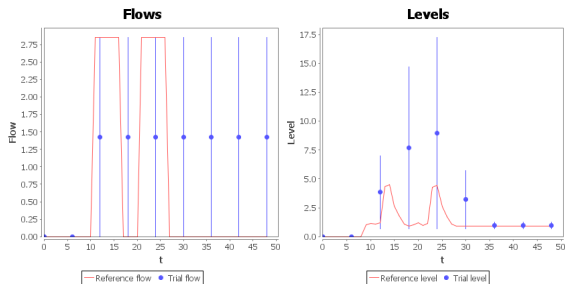




# Optimization with Intervals.

- For simple inflows (one peak) this gets stuck in an indeterminate state
- Complex algorithm
- Error margins too large for simple inputs
- Problem: defined as on at  $s(t) = s_{on}$ , problem to get  $s(t)$  below  $s_{on}$
- Work in progress

# Preliminary Results



# Summary

- Even for simple problems averaging and sampling can mislead a computer.
- For systems with feedback interval calculations may help.
- Outlook
  - More complex components.
  - components combined in series or in parallel.